Course Title	Introduction to Robotics				
Course Code	CSE225				
Course Type	Compulsory				
Level	Bachelor (1 <sup>st</sup> Cycle)				
Year / Semester	2 <sup>nd</sup> Year / 2 <sup>nd</sup> Semester				
Teacher's Name	ТВА				
ECTS	6	Lectures / week	1 hours/14 weeks	Laboratories / week	2 hours / /14 weeks
Course Purpose and Objectives	The objective of this course is to introduce students to robotics and how they are implemented in everyday life. Students will learn about the history of robotics, definitions about robotics and learn how to solve simple problems using embedded systems, sensors and actuators.				
Learning Outcomes	<ul> <li>Upon successful completion of this course, students should be able to:</li> <li>Explain how a robot works and how it can be used to solve simple problems</li> <li>Describe the various types of sensors that can be used to provide input to the robot</li> <li>Describe how actuators can be used and controlled using data retrieved from sensors</li> <li>Explain how to use creative skills such as brainstorming, vertical and lateral thinking, to solve problems using robots</li> <li>Explain the troubleshooting process for any issues in the implemented solution</li> </ul>				
Prerequisites	CSE120	Co	-requisites	None	
Course Content	Introduction to robotics: Understanding the hardware associated with a robotics platform such as the LEGO Mindstorms EV3 or the Arduino platform. Understanding what sensors and actuators are and how they can be used to solve problems. Flowcharts and Pseudocode: Building simple programs using flowcharts and pseudocode by analysing the intended operation of a robot and the required result. Understanding the sequential flow of program operation and how that can be transferred to pseudocode and then to real code. Variables and strings: Initializing variables of different datatypes such as integers, floats and strings to be used as memory storage containers in the robot. Understanding how to input and output values through the serial				
	Building a simple robot program: Learning how to formulate a simple C program that can control a basic robot. Understanding the program structur from variable declarations of basic data types, controlling power to the motors and viewing the movement of a robot. Moving forward, changing speed and direction.				imple C ram structure r to the changing

	Actuators: Understanding how actuators can be used to output information to a robot. Learning how to use DC motors, servo motors, stepper motors and other types of output devices. Sensing: Understanding how sensors work and how the input received can be used to influence actuators. Wall detection using touch sensors. Wall detection using ultrasonic sensors. Moving forwards until a specified distance. Learning how to use a color sensor. Moving forward until dark. Line tracking using color or reflected light. Creating a simple PID line following algorithm.				
	<u>Advanced variables</u> : Building variab Developing programs for robots bas values and storing them for later use	e arrays to store information. d on multiple values. Reading sensor on actuators.			
	<u>Troubleshooting</u> : Using methods to troubleshoot problems that can be identified in a robot solution.				
	Implementing more advanced robotic solutions: Identifying a more adv problem and formulating a solution using flowcharts and pseudocode. Implementing a solution using sensors and actuators to develop a mor advanced solution to a problem identified and troubleshooting the solution				
Teaching Methodology	Face-to-Face				
Bibliography	"Teaching ROBOTC for LEGO MINDSTORMS". Carnegie Mellon Univ Press				
	"Programming Arduino: Getting Started with Sketches", by Simon Monk				
	"Learn to Program in Arduino C: 18 Lessons, From setup() to Robots"				
	by William P. Osborne				
	"Beginning C for Arduino: Learn C Programming for the Arduino (Technology in Action)" by Jack Purdum Ph.D.				
	*PIC Microcontroller Projects in C: Basic to Advanced" by Dogan Ibrahim				
Assessment	Mid – Term Examination Final Examination Assignments/Lab Class Participation and Attendance	30% 30% 30% 10% 100%			
Language	English				